Adam Wei

• Cambridge, MA ☑ weiadam@mit.edu • adamwei.com **☞** Google Scholar

Education

Massachusetts Institute of Technology

Sep 2023 - Present

Ph.D. Student in Computer Science - Advisor: Prof. Russ Tedrake

o My research focuses on two main directions: 1) understanding and improving how different data sources can be used in robot imitation learning, 2) algorithmic improvements for generative modeling in robotics with a focus on learning from out-of-distribution or low-quality data.

University of Toronto

Sep 2019 - May 2023

B.Eng. in Electrical Engineering

o CGPA: 3.99/4.0

Publications & Preprints

Empirical Analysis of Sim-and-Real Cotraining of Diffusion Policies for Planar Pushing from Pixels

IROS~2025

CoRL Workshop 2025

Adam Wei, Abhinav Aqarwal, Boyuan Chen, Rohan Bosworth, Nicholas Pfaff, Russ Tedrake

How Well do Diffusion Policies Learn Kinematic Constraint Manifolds?

Under Review 2025

Lexi Foland, Thomas Cohn, Adam Wei, Nicholas Pfaff, Boyuan Chen, Russ Tedrake

Consensus Complementarity Control for Multi-Contact MPC Best Paper Award

IEEE T-RO Journal 2024

Alp Aydınoğlu, **Adam Wei**, Wei-Cheng Huang, Michael Posa

Framework and Software for Real-Time Multi-Contact Model Predictive Control

RSS 2022

Alp Aydınoğlu, Adam Wei, Michael Posa

BitAllocation: A Resource Allocation Algorithm For Fixed-Point Quantization Adam Wei, Andreas Moshovos

Preprint 2021

Talks

Learning From Out-of-Distribution Data in Robotics Slides Z Amazon Science Hub Robotics Research Day 2025	$Cambridge,\ MA \ Sep\ 2025$
Empirical Analysis of Sim-and-Real Cotraining for Diffusion Policies $CoRL\ Workshop\ 2025$	Seoul, Korea Sep 2025
Principles of Sim-and-Real Cotraining for Robot Manipulation Slides Z Amazon Consumer Robotics Symposium 2025	Sunnyvale, CA Apr 2025

Fellowships & Awards

Best Paper Award, IEEE RAS TC on Model-based Optimization for Robotics	2025
Graduate Research Fellowship, National Science Foundation	2024
Canada Graduate Scholarships-Doctoral, NSERC	2024
NDSEG Honorable Mention, US Department of Defense	2023
Gordon R. Selmon Capstone Design Award, University of Toronto	2023
ECE Top Student Award, University of Toronto	2020,2021,2022
First-Year Summer Research Fellowship, University of Toronto	2020

Work Experience

Robotics Ph.D. Student

 $Cambridge,\ MA$

Massachusetts Institute of Technology – Advisor: Prof. Russ Tedrake

Sep 2023 - Present

• My research focuses on two main directions: 1) understanding and improving how different data sources can be used in robot imitation learning, 2) algorithmic improvements for generative modeling in robotics with a focus on learning from out-of-distribution or low-quality data.

Robotics Research Assistant

Philadelphia, PA

University of Pennsylvania, GRASP Lab – Advisor: Prof. Michael Posa

May - Dec 2022

- o Developed and deployed a real-time model predictive control algorithm for multi-contact systems
- Published in the IEEE T-RO journal and received a **Best Paper Award** (see above)

Software Engineer

Toronto, Canada

Tenstorrent - AI Hardware Start-up with Jim Keller

May - Aug 2021

- \circ Developed infrastructure for our chip's kernels & backend compiler using C++, Python, SQL, and Verilog
- Awarded a bonus for demonstrating leadership skills and taking ownership of my projects

Machine Learning Research Assistant

Toronto, Canada

University of Toronto – Advisor: Prof. Andreas Moshovos

May 2020 - Dec 2021

• Developed a novel optimization-based quantization algorithm that achieved state-of-the-art compression of ImageNet models in linear-time (as opposed to existing algorithms that required exponential time)

Teaching & Service

Teaching Assistant , University of Toronto ECE421: Robot Modeling and Control – <i>Prof. Lacra Pavel</i>	Toronto, Canada Sep – Dec 2022
Graduate School Application Mentor, Massachusetts Institute of Technology MIT GAAP Program	$Cambridge,\ MA \ 2023-2024$
University of Toronto vs University of Waterloo: a Detailed Comparison Blog Post ☑	2023
Student Mentor, University of Toronto ECE Club Mentorship Program	$Toronto,\ Canada\ 2022-2023$